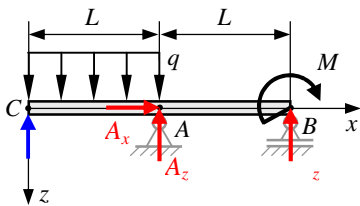


$q; M = qL^2/2; L; EI = \text{const.}$

1.

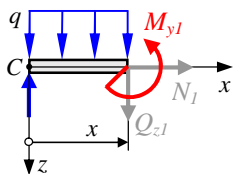
2.

$$c_{,z} = \frac{\partial U}{\partial \Phi} = \int_{L_1} \frac{M_{y1}}{EI_{y1}} \frac{\partial M_{y1}}{\partial \Phi} dx + \int_{L_2} \frac{M_{y2}}{EI_{y2}} \frac{\partial M_{y2}}{\partial \Phi} dx. \quad (1)$$



3.

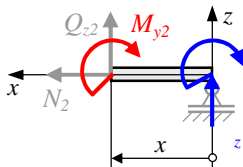
$$\begin{aligned} M_{Ai} = 0: & \quad B_z L - L - M + qL^2/2 = 0; & \quad B_z = \dots \\ M_{Bi} = 0: & \quad qL + \dots 2L + M - 3qL^2/2 = 0; & \quad z = qL - 2 \dots \\ z_i = 0: & \quad z + B_z + \dots - qL = qL - 2 \dots \end{aligned}$$



4.

4.1. (C) , $x \in [0; L]$

$$\begin{aligned} M_{yi} = 0: & \quad M_{y1} + qx^2/2 - \dots x = 0; & \quad M_{y1} = \dots x - qx^2/2; \\ & & \quad M_{y1}/ \dots = x. \end{aligned}$$



4.2. (B) , $x \in [0; L]$

$$\begin{aligned} M_{yi} = 0: & \quad M_{y2} + \dots - B_z x = 0; & \quad M_{y2} = \dots x - qL^2/2; \\ & & \quad M_{y2}/ \dots = x. \end{aligned}$$

5.

(1)

$$\begin{aligned} c_{,z} &= \frac{1}{EI_y} \int_0^L M_{y1} \frac{\partial M_{y1}}{\partial F} dx + \frac{1}{EI_y} \int_0^L M_{y2} \frac{\partial M_{y2}}{\partial F} dx = \frac{1}{EI_y} \int_0^L \left(-\frac{qx^2}{2} \right) x dx + \frac{1}{EI_y} \int_0^L \left(-\frac{qL^2}{2} \right) x dx; \\ c_{,z} &= \frac{1}{EI_y} \left[\int_0^L \left(-\frac{q}{2} x^3 \right) dx + \int_0^L \left(-\frac{qL^2}{2} \right) x dx \right] = \frac{1}{EI_y} \left[-\frac{q}{2} \frac{L^4}{4} - \frac{qL^2}{2} \frac{L^2}{2} \right]; \\ c_{,z} &= -\frac{3}{8} \frac{qL^4}{EI_y}. \end{aligned}$$